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RareBooksClub. Paperback. Book Condition: New. This item is printed on demand. Paperback. 122 pages. Original publisher: Hampton, Va. : National Aeronautics and Space Administration, Langley Research Center ; Springfield, Va. : For sale by the National Technical Information Service, 1991 OCLC Number: (OCoLC)59761145 Excerpt: . . . 5 generalizations in the world of domain-specific planning. This report further highlights the development of dynamic planner by incorporating Monte Carlo simulation techniques into situations with uncertainties. 1. 2 Outline of Report This project report is organized as follows: Chapter 2 presents a literature survey on planning and scheduling techniques for possible technology transfer into telerobotic applications. Chapter 3 presents the development of a conceptual model for planning in a telerobotic system. The concept presented is both generic and open-ended for understanding knowledge requirement in modeling teleoperation. Chapter 4 presents a task planning technique for a telerobotic environment. The methodology lies primarily on task consideration and resource needs in planning a multi-agent system. Chapter 5 presents a model for scheduling resources in a telerobotic system. A heuristic algorithm that employs results from the planning is discussed. Chapter 6 presents some sample applications in aircraft turnaround functions and simple block-world assembly problems respectively. Chapter 7 concludes the project report with a summary of what has been accomplished and a discussion of the directions for future work in planning multiagent systems with human-machine interaction in mind. This item ships from La Vergne,TN. Paperback.



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